

Last time:  $f: W \rightarrow V$  linear function

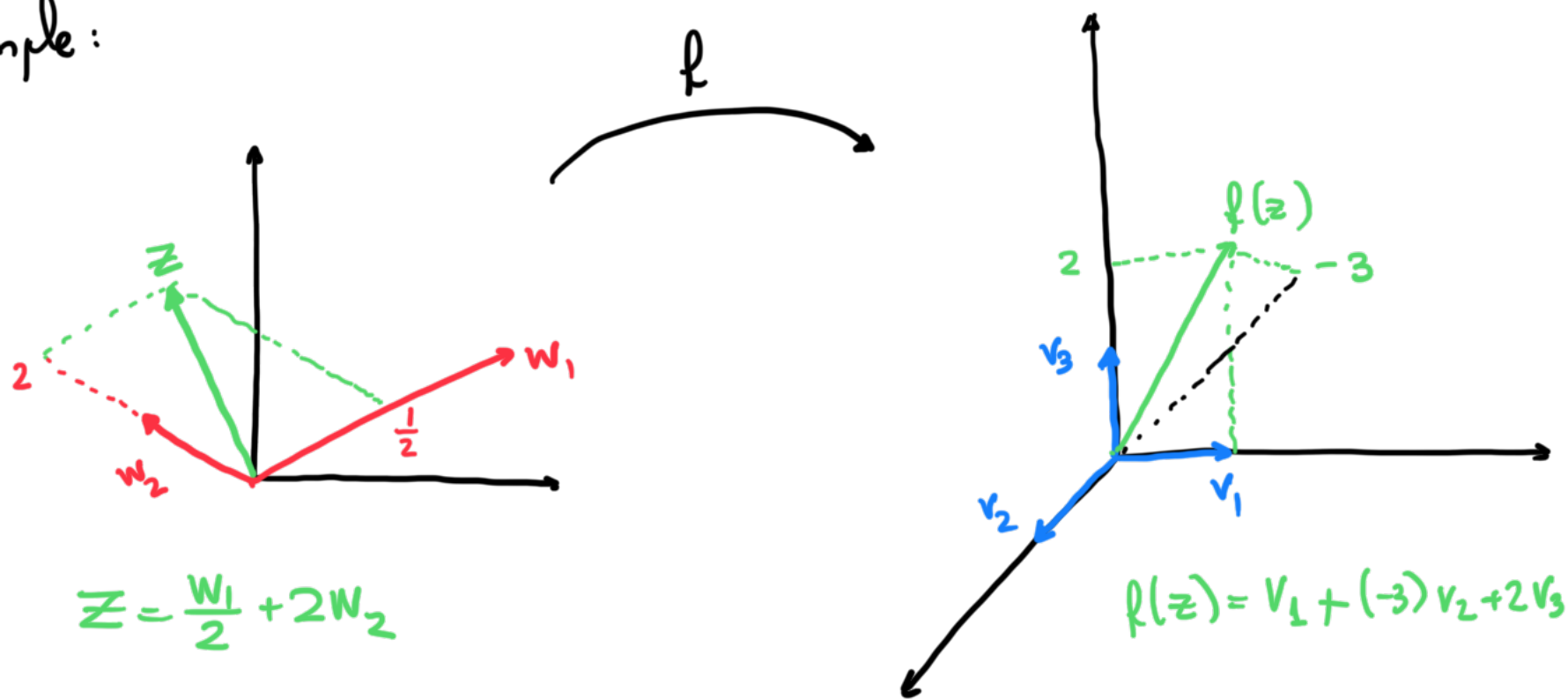
$\text{Ker}(f) \subseteq W$  are subspaces whose bases can be  
 $\text{Im}(f) \subseteq V$  computed by Gaussian elimination

given bases  $\underline{w} = (w_1, \dots, w_n)$  of  $W$  and  $\underline{v} = (v_1, \dots, v_m)$  of  $V$ ,

the linear function  $f$  is represented by a matrix  $A \in \mathbb{R}^{m \times n}$

$$[f(z)]_{\underline{v}} = A [z]_{\underline{w}}, \quad \forall z \in W$$

Example:



$\therefore A \in \mathbb{R}^{3 \times 2}$  such that

Then  $f$  is represented by a matrix  $A \in \mathbb{R}$

$$A \begin{pmatrix} \frac{1}{2} \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ -3 \\ 2 \end{pmatrix}$$



Example: consider  $V=W=\mathbb{P}_d = \{\text{polynomials of degree } \leq d\}$   
 and the bases  $\underline{v} = \underline{w} = \{1, x, \dots, x^d\}$  ↓  
dim = d+1

$T: \mathbb{P}_d \rightarrow \mathbb{P}_d$ ,  $T(\text{polynomial}) = \text{polynomial}'$

Express  $T$  by a matrix  $A \in \mathbb{R}^{(d+1) \times (d+1)}$  w.r.t. monomial bases

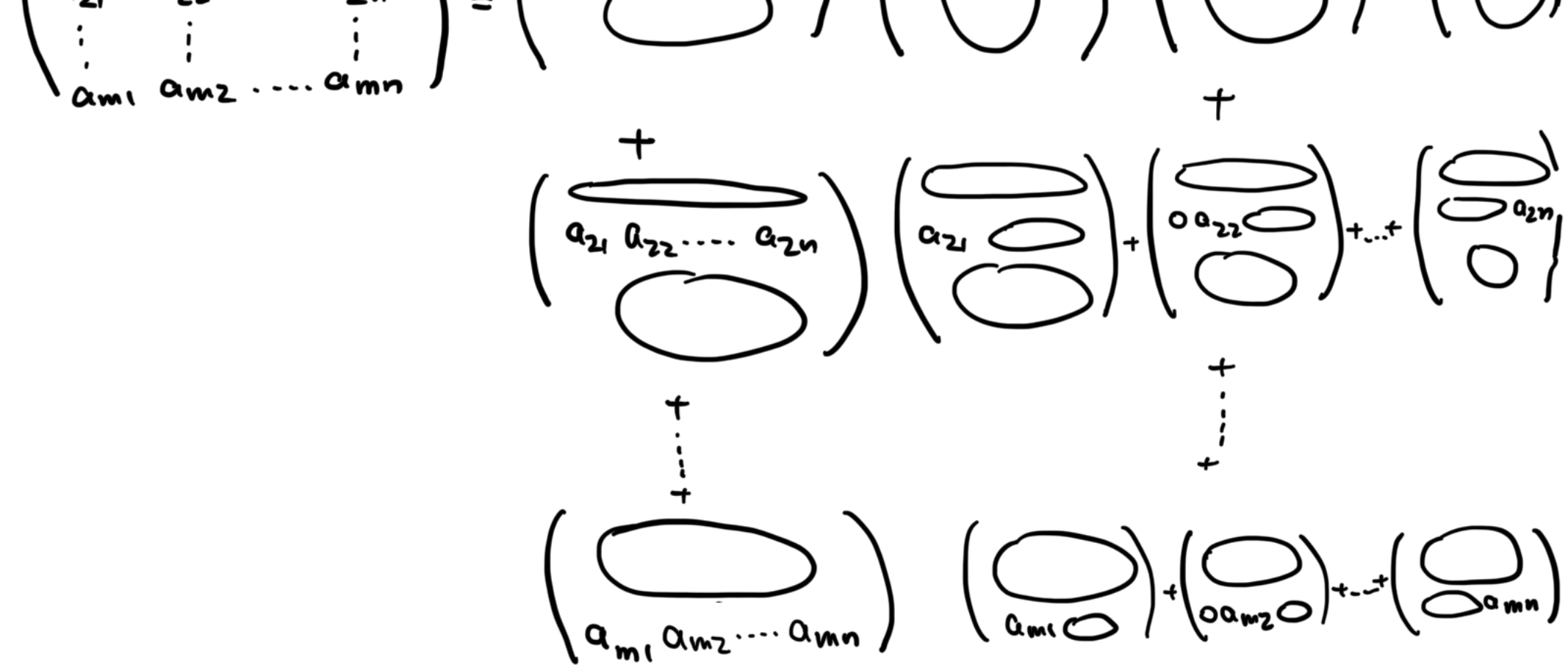
$w_1 = 1$ $w_2 = x$ $w_3 = x^2$ $\vdots$ $w_{d+1} = x^d$	$\xrightarrow{T}$	$T(w_1) = 0 = 0v_1 + 0v_2 + \dots + 0v_{d+1}$ $T(w_2) = 1 = 1v_1 + 0v_2 + \dots + 0v_{d+1}$ $T(w_3) = 2x = 0v_1 + 2v_2 + \dots + 0v_{d+1}$ $\vdots$ $T(w_{d+1}) = dx^{d-1} = 0v_1 + \dots + 0v_{d-1} + dv_d + 0v_{d+1}$	$v_1 = 1$ $v_2 = x$ $v_3 = x^2$ $\vdots$ $v_{d+1} = x^d$
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↓

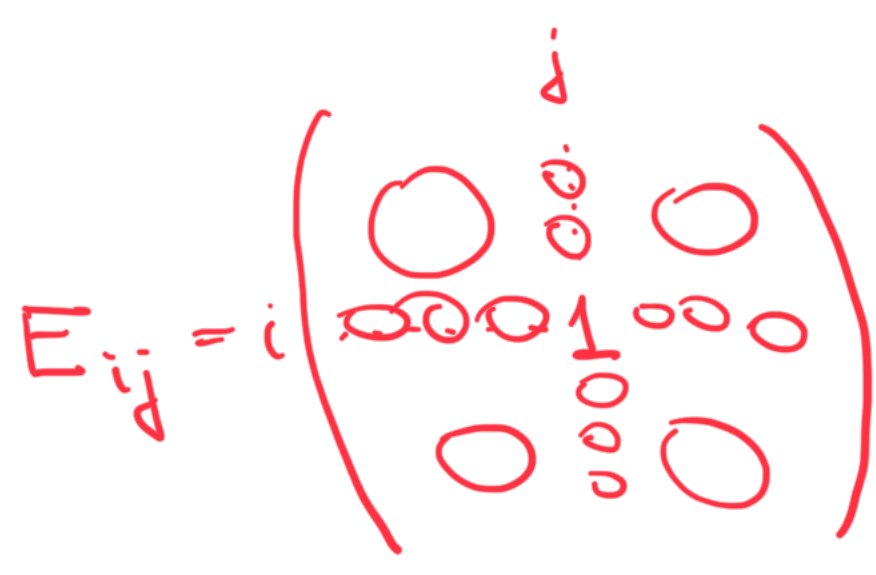
$$A = \left( \text{Exercise} \right) \in \mathbb{R}^{(d+1) \times (d+1)}$$

Example: let  $V = \mathbb{R}^{m \times n} = \{m \times n \text{ matrices}\}$  ↘ dim V = mn

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{pmatrix} = \begin{pmatrix} a_{11} & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{pmatrix} + \begin{pmatrix} 0 & a_{12} & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{pmatrix} + \dots + \begin{pmatrix} 0 & 0 & \dots & a_{1n} \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{pmatrix}$$



$$\begin{aligned}
 &= a_{11}E_{11} + \dots + a_{1n}E_{1n} \\
 &+ a_{21}E_{21} + \dots + a_{2n}E_{2n} \\
 &\quad \vdots \\
 &+ a_{m1}E_{m1} + \dots + a_{mn}E_{mn}
 \end{aligned}$$



any matrix  $A \in \mathbb{R}^{m \times n}$  can be written uniquely as a linear combination of  $\{E_{ij} \in \mathbb{R}^{m \times n} \mid 1 \leq i \leq m, 1 \leq j \leq n\}$

e.g.  $\begin{pmatrix} 2 & 3 \\ 9 & 5 \end{pmatrix} = 2E_{11} + 3E_{12} + 9E_{21} + 5E_{22}$

a basis of  $\mathbb{R}^{m \times n}$

$T: \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}^{2 \times 2}$ ,  $T(B) = B^T$  a linear function

$\downarrow$  4-dim v.s.       $\downarrow$  4-dim v.s.       $\downarrow$  2x2

what matrix  $A$  corresponds to the function  $T$  w.r.t to the bases  $\{E_{11}, E_{12}, E_{21}, E_{22}\}$  of  $\mathbb{R}^{2 \times 2}$ ? Must have  $A \in \mathbb{R}^{4 \times 4}$

$$w_1 = E_{11}$$

$$w_2 = E_{12}$$

$$w_3 = E_{21}$$

$$w_4 = E_{22}$$



$$T(w_1) = E_{11} = 1v_1 + 0v_2 + 0v_3 + 0v_4$$

$$T(w_2) = E_{21} = 0v_1 + 0v_2 + 1v_3 + 0v_4$$

$$T(w_3) = E_{12} = 0v_1 + 1v_2 + 0v_3 + 0v_4$$

$$T(w_4) = E_{22} = 0v_1 + 0v_2 + 0v_3 + 1v_4$$

$$v_1 = E_{11}$$

$$v_2 = E_{12}$$

$$v_3 = E_{21}$$

$$v_4 = E_{22}$$

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

New topic:

DEF 15.1: An **isomorphism** is a

bijective / invertible linear function  $f: W \rightarrow V$

$$W \cong V \quad (\text{"W is isomorphic to V"})$$

- $V \cong V$

- if  $V \cong W$  then  $W \cong V$  (if  $\exists f$  going one way, then  $f^{-1}$  goes the other way)

- if  $V \cong W$  and  $W \cong Z$  then  $V \cong Z$

THEM 15.2: If  $V \cong W$  then

# THM 15.2: $f: V \rightarrow W$ , $\dim(V) = \dim(W) = n$

- $v_1, \dots, v_n$  are linearly independent in  $V$   
 $\Downarrow$   
 $f(v_1), \dots, f(v_n)$  are linearly independent in  $W$
- $v_1, \dots, v_n$  span/generate  $V$   
 $\Updownarrow$   
 $f(v_1), \dots, f(v_n)$  span/generate  $W$
- $v_1, \dots, v_n$  are a basis of  $V$   
 $\Downarrow$   
 $f(v_1), \dots, f(v_n)$  are a basis of  $W$  }  $\Rightarrow \dim(V) = \dim(W)$

based on the following fact:

$$v = c_1 v_1 + \dots + c_n v_n \iff f(v) = c_1 f(v_1) + \dots + c_n f(v_n)$$

THM 15.3: any vector space  $V$  of dimension  $n$  is isomorphic to  $\mathbb{R}^n$

$\Downarrow$   
up to isomorphism, any v.s. of dim 0 is  $\mathbb{R}^0 = \{0\}$   
any v.s. of dim 1 is  $\mathbb{R}^1$  } finite

any v.s. of dim 2 is  $\mathbb{R}^2$

⋮

any v.s. of dim  $\infty$  is " $\mathbb{R}^\infty$ "

} dim  
v.s.

Proof of Thm 15.3:  $\dim(V) = n$

↓

$V$  has a basis  $\underline{v} = \{v_1, \dots, v_n\}$

define  $f: V \rightarrow \mathbb{R}^n$ ,  $f(z) = [z]_{\underline{v}}$   $\forall z \in V$

Claim  $\rightarrow$   $f$  is linear, i.e.  $f(c_1 z_1 + c_2 z_2) = [c_1 z_1 + c_2 z_2]_{\underline{v}} = c_1 [z_1]_{\underline{v}} + c_2 [z_2]_{\underline{v}} = c_1 f(z_1) + c_2 f(z_2)$

$\rightarrow$   $f$  is injective, i.e. diff.  $z \neq z'$  should have diff. coordinates

$\rightarrow$   $f$  is surjective, i.e.  $\forall \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix} \in \mathbb{R}^n$ ,  $\exists z \in V$  s.t.  $[z]_{\underline{v}} = \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix}$

$\parallel$   
 $c_1 v_1 + \dots + c_n v_n$

↓

$f$  is an isomorphism

Ex:  $V = \mathbb{R}^n$   $\underline{v} = (v_1, \dots, v_n)$  an arbitrary basis of  $\mathbb{R}^n$

$f: V \rightarrow \mathbb{R}^n$ ,  $f(z) = [z]_{\underline{v}}$ ,  $\forall z \in V$

$\parallel$   
 $\mathbb{R}^n$

$\parallel$   
 $\mathbb{R}^n$

$\parallel$   
 $\mathbb{R}^{n \times n}$

$$f(z) = Az \quad \text{for a matrix } A \in \mathbb{R}^m$$

Claim:  $A = P_{\underline{v}}^{-1} = P_{\underline{e} \leftarrow \underline{v}}^{-1} = P_{\underline{v} \leftarrow \underline{e}}$ , because  $\forall z \in \mathbb{R}^n$ ,

change of coordinate matrix from one basis to another

$$P_{\underline{v} \leftarrow \underline{e}} z = [z]_{\underline{v}}$$

$$z = P_{\underline{e} \leftarrow \underline{v}} [z]_{\underline{v}}$$

checks out for  $z = v_i$

$$\text{coordinates of } v_i = \begin{pmatrix} a_{1i} \\ \vdots \\ a_{ni} \end{pmatrix} =: P_{\underline{e} \leftarrow \underline{v}} \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$$

Big picture stuff:  $W$  of dim  $n \rightsquigarrow$  basis  $\underline{w} = \{w_1, \dots, w_n\}$   
 $V$  of dim  $m \rightsquigarrow$  basis  $\underline{v} = \{v_1, \dots, v_m\}$

suppose you have a linear function  $W \xrightarrow{f} V$   
 and you want to find the  $m \times n$  matrix  $A$  which represents it

$$\Phi: \mathbb{R}^n \xrightarrow{h^{-1}} W \xrightarrow{f} V \xrightarrow[\cong]{g} \mathbb{R}^m$$

where  $\alpha: V \xrightarrow{\cong} \mathbb{D}^m$   $\alpha(z) = [z]_{\underline{v}}$

$$h: W \xrightarrow{\sim} \mathbb{R}^n, \quad h(z) = [z]_{\underline{w}}$$

$$\Phi = g \circ f \circ h^{-1}: \mathbb{R}^n \rightarrow \mathbb{R}^m \quad \text{linear}$$

corresponds to  $A \in \mathbb{R}^{m \times n}$ ; this is precisely the matrix which represents  $f$

$$\begin{array}{l} \text{Ex:} \\ W = \mathbb{P}_2 \\ V = \mathbb{P}_3 \end{array} \quad \begin{array}{l} \underline{w} = \{1, x, x^2\} \\ \underline{v} = \{1, x, x^2, x^3\} \end{array}$$

$$f: W \rightarrow V, \quad f(\text{polynomial}) = \text{polynomial} \cdot (1+2x)$$

$$A \in \mathbb{R}^{4 \times 3}; \quad \text{let's find } A$$

$$\begin{array}{c} \Phi: \mathbb{R}^3 \longleftarrow \mathbb{P}_2 \xrightarrow{\text{mult by } (1+2x)} \mathbb{P}_3 \xrightarrow{\sim} \mathbb{R}^4 \\ \begin{array}{l} e_1 \rightsquigarrow 1 \\ e_2 \rightsquigarrow x \\ e_3 \rightsquigarrow x^2 \end{array} \quad \begin{array}{l} 0 \\ 1 \\ x \\ x^2 \\ x^3 \end{array} \rightsquigarrow \begin{array}{l} e_1 \\ e_2 \\ e_3 \\ e_4 \end{array} \end{array}$$

$$e_1 \rightsquigarrow 1 \rightsquigarrow 1+2x \rightsquigarrow e_1 + 2e_2 = \Phi(e_1)$$

$$e_2 \rightsquigarrow x \rightsquigarrow x+2x^2 \rightsquigarrow e_2 + 2e_3 = \Phi(e_2)$$

$$e_3 \rightsquigarrow x^2 \rightsquigarrow x^2 + 2x^3 \rightsquigarrow e_3 + 2e_4 = \Phi(e_3)$$

$$\text{So } A = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{pmatrix}$$